

Vertex reconstruction in CMS

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Outline

- · Introduction: tasks, boundary conditions
- · Vertex fitting
- Vertex finding
- Testing
- · Conclusions



Introduction

Tasks

- · Fitting of a single vertex
 - most precise vertex position and track parameters at vertex
- · Vertex finding
 - separation of primary vertices (presentation from D.Kotlinski)
 - · search for (at least 1) secondary vertex inside a jet
 - typical application: b-jet tagging
 - reconstruction of decay chains



Boundary conditions

Separation of primary vertices along beam axis

- · At high LHC luminosity: <17> primary vertices, 1 hard event, spread with σ_z = 5.3 cm
- CMS Tracker resolution on longitudinal impact parameter z_0 :

•
$$\sigma(z_0)$$
 = $f(p_T, \eta)$
 p_T = 1 GeV/c: 90 \rightarrow 800 μ m
high p_T : 20 \rightarrow 80 μ m

- ⇒ Hard event easy to separate in z
- ⇒ Search for secondary vertex can proceed in Region Of Interest defined by (CALO jet cone + primary vertex)
 - ⇒ Association of tracks to primary vertex: less easy



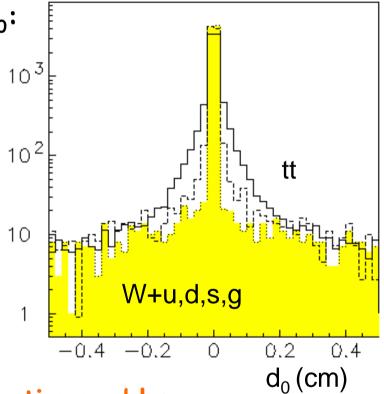
Boundary conditions (2)

Search for secondary vertex inside b-jet

· Resolution on transverse impact parameter d₀:

• $\sigma(d_0)$ = $f(p_T,\eta)$ p_T = 1 GeV/c: 80 \rightarrow 200 μ m high p_T : 10 \rightarrow 20 μ m

- · d₀ in top pair, W+c, W+u,d,s,g-events:
 - · impact parameter of secondaries ~ mm
- · A few percent of mismeasured tracks, with much worse resolution



⇒ Interesting association / minimization problem
 ⇒ 3D reconstruction should work better than reconstruction in transverse plane only



Vertex fitting

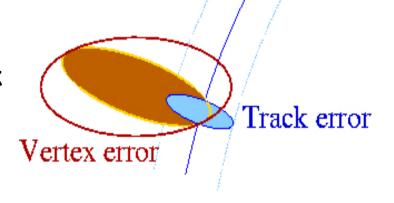
Principle

- Minimization problem
 - · minimize a function of track-to-vertex distances
- Each track constrains the vertex by a helix + error (2D constraint)
- · Non-linear, but explicit linear solution exists if tracks are linearized in the vicinity of the vertex position
 - requires a first guess of vertex position, and iterations if fitted position is too far from first guess

P.Vanlaer, IIHE Brussels

Techniques

- · Least sum of Squares (LS):
 - · all tracks are used unweighted
 - function to minimize is usual total χ^2
 - biased if vertex contains an outlier, i.e. track from another vertex or badly measured track
- · Robust estimators:
 - insensitive to outliers

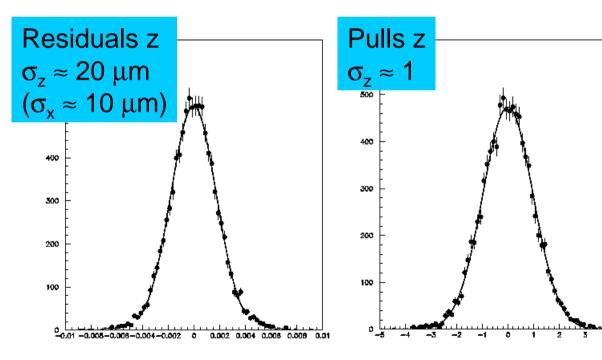




LS: Linearized vertex fit

Very fast, precise algorithm (V.Karimäki, HIP-1997-77/EXP)

- · straight line approximation of tracks at linearization point
 - correct to a few μm for $p_T > 1$ GeV/c if d(lin.point-vtx) < few mm
- track error matrix ~ constant around lin.point
- · explicit solution involving only 3x3 matrix algebra



10000 H→4µ events LinearVertexFitter

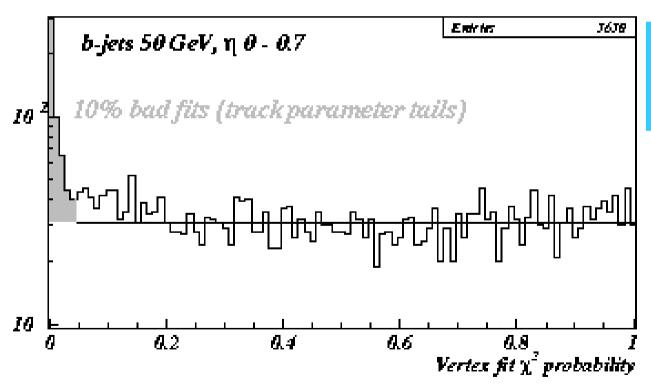
Kirill Prokofiev, Thomas Speer

lin.p.
i.p. wrt. lin.p.
Line constraint



Linearized vertex fit (2)

- Distribution of χ^2 probability
 - ~flat as expected
 - powerful test to reject fake vertices
 - 10% bad fits due to tails of d_0 and z_0 pull distributions



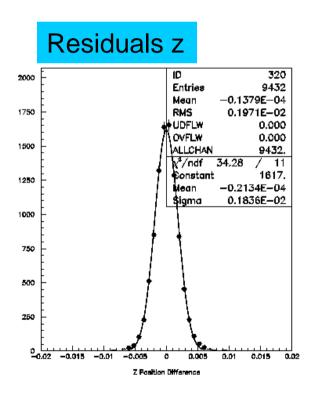
All vertices in *b*-jets $P(\chi^2)$, tracks selected using MC information

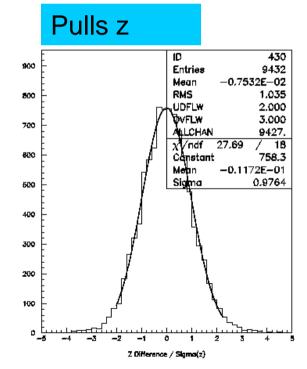


LS: Kalman vertex fit

Kalman formalism (R.Frühwirth et al.)

- · allows parabolic track approximation instead of straight line
 - should be more precise for low p_T tracks
 - should require less iterations





10000 H→4µ events KalmanVertexFitter

Identical performance as LinearVertexFitter for high p_T tracks

Kirill Prokofiev, Thomas Speer



Robust estimators

Robust = insensitive to outlying tracks

- · most distant tracks discarded (Least Trimmed Squares, Least Median of Squares, Minimum Volume Ellipsoid, Minimum Covariance Determinant,...)
- · distant tracks downweighted (M-estimator, adaptive algorithms,...)
- · CPU-expensive but fast, approached algorithms exist (tried here)

Least Trimmed Squares (P.Rousseeuw et al.)

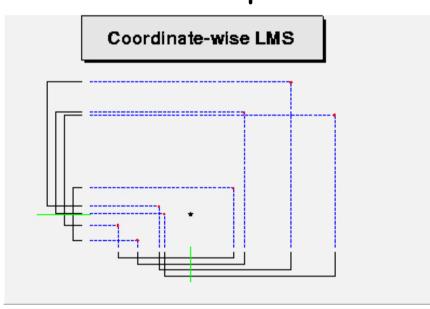
- use k most compatible tracks out of N(k/N): trimming fraction)
- breakdown point $\approx 1-k/N$
- · has good statistical properties
 - estimator has normal distribution, precision improves as 1/sqrt(N)
- \cdot Exhaustive: try all possible combinations of k out of N
- · FAST-LTS: good approached iterative algorithm



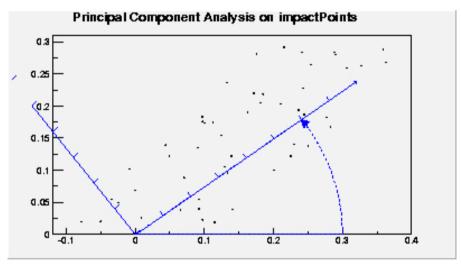
Robust estimators (2)

Least Median of Squares (P.Rousseeuw et al.)

· Fast implementation: medians of coordinates of track impact points wrt. linearization point:



+ Principal Component Analysis



- very robust (breakdown point = 0.5)
- worse statistical properties
 - not normal, precision improves as $N^{-1/3}$

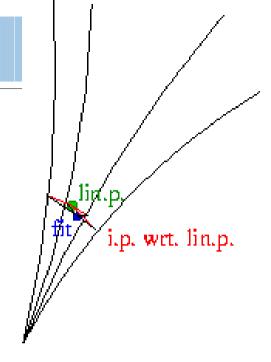


Robust estimators (3)

Least Median of Squares (cont.)

· this implementation: sensitive to choice of initial linearization point

⇒ Fast, precise linearization point finder: LMS on crossing points of track pairs



Adaptive vertex fit

· iterative, re-weighted LS fit

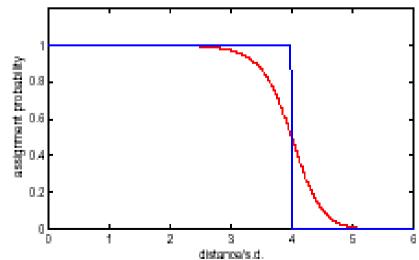
 \cdot weight w of track i at iteration k depends on

distance r to vertex at iteration k-1

• $w(r) \equiv assignment probability$

· same good properties as LS estimators

Examples of weight functions w(r) for a cut at r = 4





Robust estimators: results

	Mean (mkm)	RMS (mkm)	Failed	msec./fit 1GHz PC
Linear	50	45	none	15
LMS*"	85	160	none	13
LTS (0.8)	16	26	none	65
MCD (0.8)	21	19	none	62
Adaptive**	50	45	none	29

300 vertices from VertexGun 50 tracks + 5 outliers Mean and RMS of distance(sim - rec) *no error matrix estimation "2tk lin. point finder **very preliminary Wolfgang Waltenberger

- robustness pays in precision
- · CPU not so bad (only factor 4 slower than linearized LS fit)

VertexFitter /	Mean RMS		msec./fit
LinPointFinder	(mkm)	(mkm)	1GHz PC
LTS(0.95) / 2tk	43	50	76
LTS(0.95) / LMSLP	15	10	58

50 vertices from VertexGun 50 tracks + 2 outliers

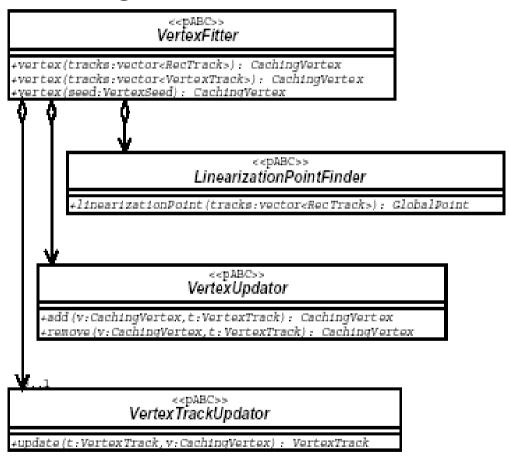
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- robust estimators sensitive to linearization point
- · LMS on crossing points of track pairs seems to works well

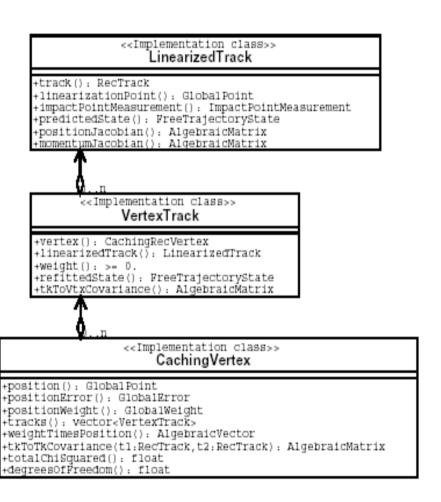


Decomposition in classes

UML diagrams:



All functional components are clonable





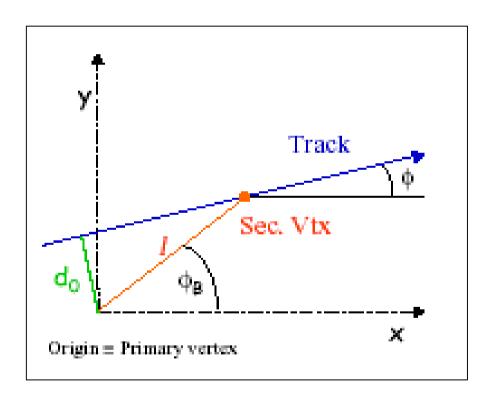
Vertex finding

Variety of algorithms (R.Frühwirth, CMS mini-workshop on vtx reconstruction)
Two simple working algorithms in CMS

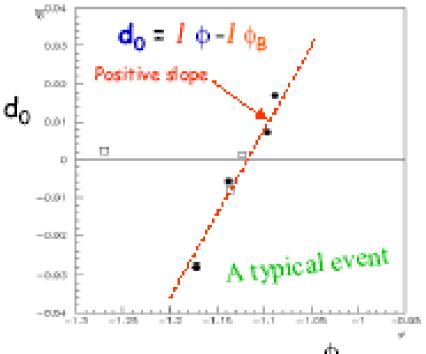
- - exploits correlation between d_0 and ϕ for tracks from same vertex
- Principal vertex finding
 - finding-trough-fitting: fits all tracks to a common principal vertex, discards incompatible tracks, then looks for a secondary vertex among discarded tracks
- More evolved algorithms (competitive learning, multi-vertex fitting,...) need guess of number and position of vertices
 basic building blocks are:
 - · a vertex fitting algorithm (LS, LTS, adaptive,...)
 - · a vertex seed generator
 - · Minimum Spanning Tree, Self-Organizing Map,...
 - · development started (Eric Chabanat, Nicolas Estre)



D0¢ algorithm

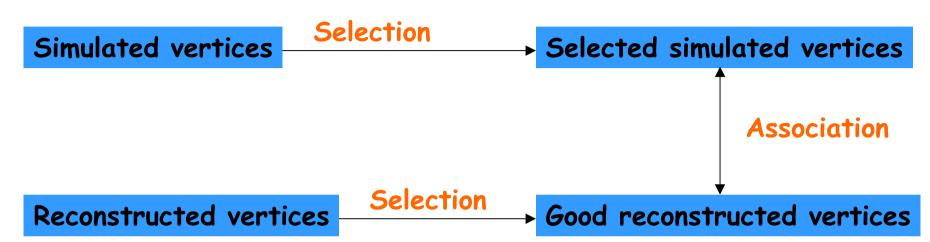


- · in (d0, ϕ) plane
 - 1 point for each track
 - points from same secondary vertex aligned
 - form segments of positive slope and cluster them





Analysis



Tommaso Boccali

- · A simulated vertex is found if there is an associated reconstructed vertex
- · A reconstructed vertex is a fake if there isn't any associated simulated vertex
- Association is done by tracks
 - a reconstructed vtx is associated to the simulated vtx from which the largest fraction of its tracks originate



Analysis (2)

Vertex selection

- · simluated vertices: >= 2 reconstructed tracks
- · reconstructed vertices: > 55% of tracks from same sim. Vtx

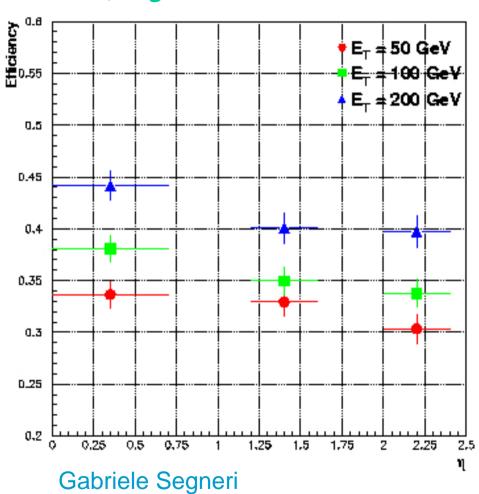
Event samples

- · di-jet events, E_T = 50, 100 and 200 GeV, 0 < η < 2.4
- · b-jets: secondary vtx finding efficiency
- · u-jets: fake rate



Results

DO\$\phi\$ algorithm



Principal vertex reconstruction

Principal vertex		Fake rate
reconstructor	(%)	(fake/uu ev.)
ET = 50 GeV, all eta	33	0.006
100 GeV	36	0.009
200 GeV	32	

Pascal Vanlaer

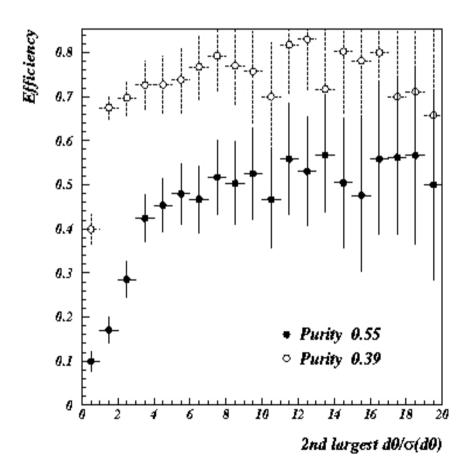
- · Comparable results
- · Fake rate very low
- · Low efficiency... see next slide



Results (2)

Efficiency vs.

- separation of secondary vertex from beam
- selection of reconstructed vertices



S.V. finding efficiency vs. 2nd largest transverse impact parameter, 50 GeV b-jets, all η Principal vertex reconstructor

In summary:

- secondary vertices with small separation from beam ARE found (efficiency ≈ 70%)
- but up to 60% of their tracks do not originate from the right vertex

Replace LS by robust fitter to improve:

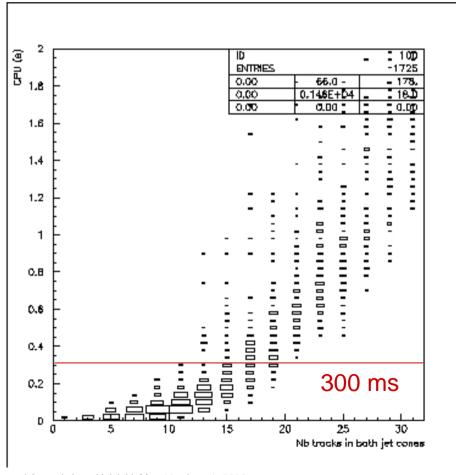
- primary vertex position thus separation of secondaries from primary vertex
- secondary vertex purity



Results (3)

Use of secondary vertex finding online

- · Principal vertex reconstruction applied jet per jet
- · CPU vs. number of tracks in both jets (1GHz PC, 50 GeV b-jets)



Even inclusive search seems affordable online (after some optimization)

- \cdot CPU time available @ CMS L2 \equiv 300 ms on today 1GHz CPU
- · sizeable fraction of events processed in less than 300 ms

Pascal Vanlaer



Testing

Vertex reconstruction is at the end of event reconstruction chain

- · affected by problems upstream
- · use of full chain (database access; event simulation and track reconstruction if not done yet) for simple algorithm tests too slow

VertexGun facility:

- allows generation of user-defined kinematics at vertex
- · provides coarse track parameter smearing + error matrix
- · ideal for e.g. code release tests

Wolfgang Waltenberger

Fast Tracker Simulation (FTSim) facility:

- · parametrizes track reconstruction performance
- · tuned on full reconstruction
- provides handles to deteriorate / improve track parameter resolutions and tails
- · ideal for e.g. stability tests wrt. tracker performance



Conclusions

CMS vertex reconstruction code offers:

- · fast, precise and reliable vertex fitting tools
- · secondary vertex finding algorithms with satisfactory performance
 - improvements on CPU time for online: in progress
 - improvements on vertex purity for offline: in progress
- many performance analysis tools, still being completed
- · code gets more and more used in analyses

Developing rapidly:

- robust vertex fitting algorithms
 - · building blocks for advanced vertex finding algorithms
- · several tried for the first time in HEP
- · testing facilities for fast algorithm development

Material, references,...: CMS b/τ page -> Activities -> Vertex; CMS b/τ page -> Mini-workshops